



NARSIMHA REDDY ENGINEERING COLLEGE

(Autonomous)

Approved by AICTE, New Delhi & Affiliated to JNTUH, Hyderabad

Accredited by NBA & NAAC with A Grade

SYLLABUS

Prerequisite: Linear Algebra and Calculus, Ordinary Differential Equations and Multivariable Calculus Laplace Transforms, Numerical Methods and Complex variables

Course objectives:

- To understand the different ways of system representations such as Transfer function representation and state space representations and to assess the system dynamic response
- To assess the system performance using time domain analysis and methods for improving it
- To assess the system performance using frequency domain analysis and techniques for improving the performance
- To design various controllers and compensators to improve system performance

Course Outcomes: At the end of this course, students will demonstrate the ability to

- Understand the modeling of linear-time-invariant systems using transfer function and State space representations.
- Understand the concept of stability and its assessment for linear-time invariant systems.
- Design simple feedback controllers.

UNIT - I

Introduction to Control Problem: Industrial Control examples. Mathematical models of physical systems. Control hardware and their models. Transfer function models of linear time-invariant systems.

Feedback Control: Open-Loop and Closed-loop systems. Benefits of Feedback. Block diagram algebra.

UNIT - II

Time Response Analysis of Standard Test Signals: Time response of first and second order systems for

standard test inputs. Application of initial and final value theorem. Design specifications for second order systems based on the time-response. Concept of Stability. Routh-Hurwitz Criteria. Relative Stability analysis. Root-Locus technique. Construction of Root-loci.

UNIT - III

Frequency-Response Analysis: Relationship between time and frequency response, Polar plots, Bode plots. Nyquist stability criterion. Relative stability using Nyquist criterion – gain and phase margin. Closed-loop frequency response.

UNIT - IV

Introduction to Controller Design: Stability, steady-state accuracy, transient accuracy, disturbance rejection, insensitivity and robustness of control systems. Root-loci method of feedback controller design. Design specifications in frequency-domain. Frequency-domain methods of design. Application of Proportional, Integral and Derivative Controllers, Lead and Lag compensation in designs. Analog and Digital implementation of controllers.

UNIT - V

State Variable Analysis and Concepts of State Variables: State space model. Diagonalization of

State Matrix. Solution of state equations. Eigen values and Stability Analysis. Concept of controllability and observability. Pole-placement by state feedback. Discrete-time systems. Difference Equations. State-space models of linear discrete-time systems. Stability of linear discrete-time systems.

TEXT BOOKS:

1. M. Gopal, "Control Systems: Principles and Design", McGraw Hill Education, 1997.
2. B. C. Kuo, "Automatic Control System", Prentice Hall, 1995.

REFERENCE BOOKS:

1. K. Ogata, "Modern Control Engineering", Prentice Hall, 1991.
2. I. J. Nagrath and M. Gopal, "Control Systems Engineering", New Age International, 2009